

Sheet 1 of 1

Substitute Form PTO-1449 (Modified) Information Disclosure Statement by Applicant (Use several sheets if necessary) (37 CFR §1.98(b))	U.S. Department of Commerce Patent and Trademark Office	Attorney's Docket No. 13909-123001	Application No. 10/691,971
	Applicant Peter Ebert		
	Filing Date October 24, 2003	Group Art Unit 3661	

U.S. Patent Documents							
Examiner Initial	Desig. ID	Document Number	Publication Date	Patentee	Class	Subclass	Filing Date If Appropriate

Foreign Patent Documents or Published Foreign Patent Applications								
Examiner Initial	Desig. ID	Document Number	Publication Date	Country or Patent Office	Class	Subclass	Translation	
							Yes	No
m.m	AA	EP 1 092 458 A	04/18/2001	EPO	—	—	<input checked="" type="checkbox"/>	
m.m	AB	WO 02/081156 A	10/17/2002	WIPO	—	—	<input checked="" type="checkbox"/>	
m.m	AC	WO 03/060752 A	07/24/2003	WIPO	—	—	<input checked="" type="checkbox"/>	

Other Documents (include Author, Title, Date, and Place of Publication)		
Examiner Initial	Desig. ID	Document
m.m	AD	Anousaki, G.C., et al., "Simultaneous Localization and Map Building for Mobile Robot Navigation," <u>IEEE Robotics & Automation Magazine</u> , v. 6, no. 3, September 30, 1999, pp. 42-53, XP002295580
m.m	AE	Freund, E., et al., "Intelligent Autonomous Robots for Industrial and Space Applications," September 12, 1994, <u>Proceedings of the IEEE/RSJ/GI International Conference on Intelligent Robots and Systems: Advanced Robotics and the Real World</u> , Munich, Germany, XP000514615, 8 pgs.
m.m	AF	Freund, E., et al., "Toward Realistic Simulation of Robotic Workcells," <u>Advanced Robotic Systems and the Real World</u> , September 12, 1994, <u>Proceedings of the IEEE/RSJ/GI International Conference on Intelligent Robots and Systems: Advanced Robotics and the Real World</u> , pp. 39-46, XP010141842

Examiner Signature <i>McDiarmid Marc</i>	Date Considered 10-1-05
EXAMINER: Initials citation considered. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.	